



Product Manual

Product Model: EM-CA-89-C

Product version number: v1.0



Ningbo ENVO Robot Co. Ltd

1. Precautions

1.1 Usage Requirements

Before using this product, users must carefully read this manual and follow its instructions. The company assumes no responsibility for any property damage or personal injury resulting from failure to comply with this manual. Due to the complexity of product components, keep the product out of reach of children to prevent accidents.

Operate the product within the specified working parameters. Do not exceed parameter ranges or use in high-temperature/high-pressure environments, as this may cause irreversible damage.

Before use, check that all components are intact. If any parts are missing or damaged, please contact us via our official website or scan the QR code at the bottom of this manual for technical support.

This manual has been compiled to include all available function descriptions and usage instructions at the time of printing. However, due to continuous product iteration, discrepancies may exist with the product you purchased. If you notice any inconsistencies, contact us promptly for technical support.

Do not remove or damage the SN label on the product. If you encounter any product issues, this label serves as an essential reference for product support.

1.2 Electrical Safety

Ensure no short circuits when connecting the motor. Connect interfaces according to the specified pinout.

Ensure the motor operates within its permitted voltage range.

1.3 Prohibition of Disassembly, Modification, and Overuse

Do not disassemble the motor arbitrarily, as this may damage components and lead to irrecoverable faults.

Do not modify motor properties while the actuator is running.

2. Model Definition

Model Definition: EM-CA-89-29-(SE/DE/CO/D/B)

Others:

SE: Single Encoder

DE: Dual Encoder

CO: CANopen Communication

D: Multi-turn Absolute Encoder

B: Brake

Gear Ratio

Outer Diameter, Unit: mm

Drive Category

Series Number

Envo Motor abbreviation

This definition applies to various series of products of actuator motors



3. Product Information

This product is a integrated cycloidal drive actuator, model: EM-CA-89-29.

This product is purpose-built for modern robotic actuation, featuring exceptional impact resistance, high-precision transmission, and high load capacity. It empowers robots to achieve more stable, durable, and resilient motion..With a modular split design, it accommodates diverse customer customization needs while achieving extreme lightweight construction, easily adapting to compact robot actuator layouts..

2.1 Main Parameters

Drive Type: Cycloidal drive

Motor Type: Frameless Inner Rotor

Backlash: 5 arcmin

Gear Ratio: 29

Rated Current: 6.6 Apk

Peak Current: 19.5 Apk

Rated Torque: 25 Nm

Peak Torque: 95 Nm

Rated Speed: 83 rpm

Peak Speed: 101 rpm

Phase-to-Phase Resistance: 330 mΩ

Phase-to-Phase Inductance: 0.51 mH

Motor Demagnetization Temperature: 110 °C

Weight: 1320 g

2.2 Operating Standards

Rated Voltage: DC 48 V

Voltage Range: DC 24-55 V

Standard Operating Temperature: 20±10 °C

Operating Temperature Range: -20-50 °C

Standard Operating Humidity: 65 %

Operating Humidity Range: 5-85 %, non-condensing

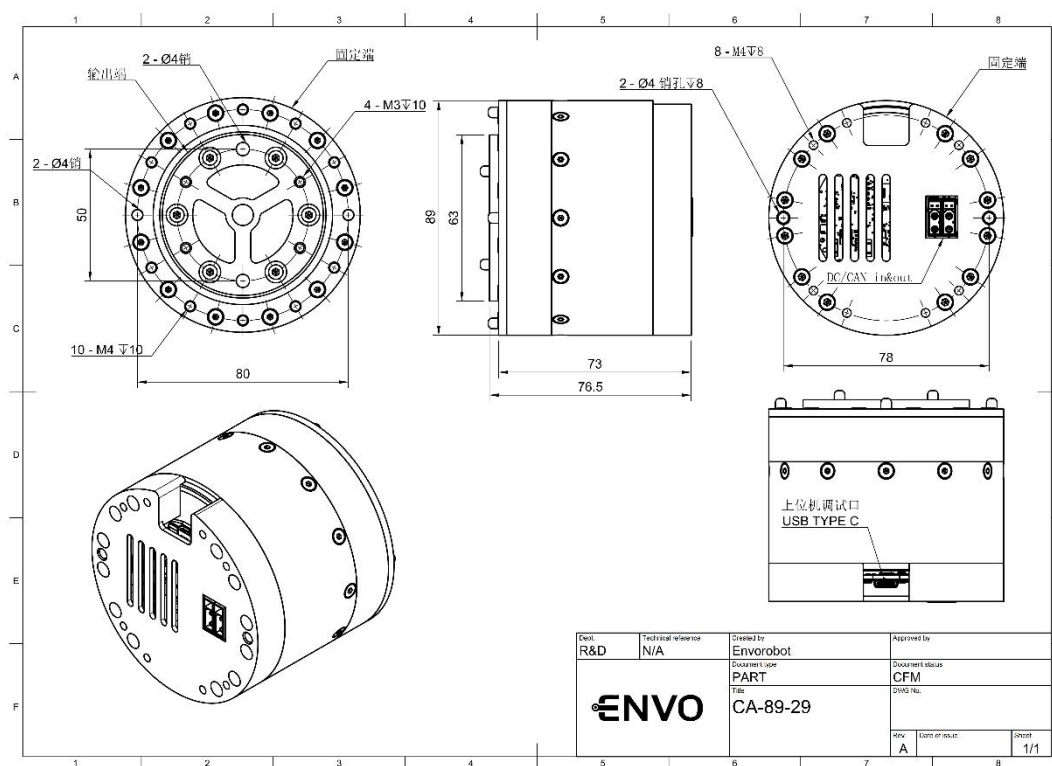
Storage Temp Range: -30-70 °C

2.3 Installation

Download 3D model:

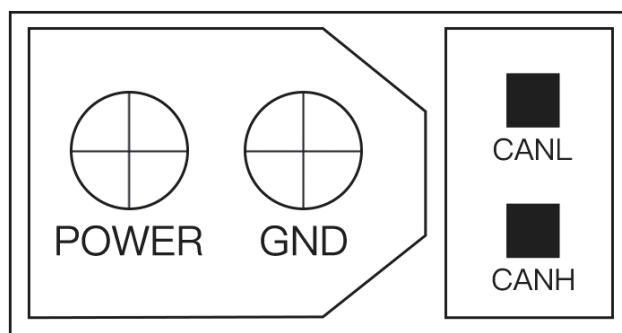
EM-CA-89-External.step

Installation Dimensions:



2.4 Motor Driver Product Information

Interface Diagram



Drive Mode: FOC

Number of Encoders: 1

Max. Motor Driver Board Temp: 100 °C

CAN Bus Max Baud Rate: 4 Mbps (default 1 Mbps)

4. Communication

Communication Mode:

Supported communication modes: Serial mode (for host PC only) and multiple CAN modes

Mode Switching:

Long-press the button for 4+ seconds to enter communication mode setup:

Press once to switch to Serial mode, baud rate: 921600 bps, LED blinks once;

Press twice to switch to CAN mode, baud rate: 500 Kbps, LED blinks twice;

Press 3 times to switch to CAN mode, baud rate: 1 Mbps, LED blinks 3 times;

Press 4 times to switch to CAN-FD mode, baud rate: 4 Mbps, LED blinks 4 times;

After switching, a restart is required for the changes to take effect.

ENVO MOROR (M) CANCAN Communication Manual

5. Host Computer Software

Download Host Computer Software:

[envo.zip](#)

Download User Manual:

[Host Computer Software User Manual](#)

6. Technical after-sales and contact information

Email: RobotActuator@envorobot.com

Address: Room 202, Building 1, Shangzheng Zhigu Science Park, Qiantang District, Hangzhou, Zhejiang, China

WeChat: EnvoRobot

Youtube: Envo Robot

LinkedIn: Chuanfu He